



IPDIMS 2021



3rd Innovative Product Design and Intelligent Manufacturing Systems

Certificate of Participation

This is to certify that Hare Shankar Kumhar of National Institute of Technology, Uttarakhand presented the paper titled Inverse Kinematic Solution for 6 - R Industrial Robot Manipulator using Convolution Neural Network co-authored by Hare Shankar Kumhar, Vikas Kukshal at the international conference on 3rd Innovative Product Design and Intelligent Manufacturing Systems (IPDIMS) during 30th & 31st December 2021, jointly organized by Department of Industrial Design and Department of Mechanical Engineering of NIT, Rourkela.


Dean (SRICCE)
NIT Rourkela


Prof. D R K Parhi
Chairman, IPDIMS'21


Prof. B B V L Deepak
Convener, IPDIMS'21